

Rotation rate?

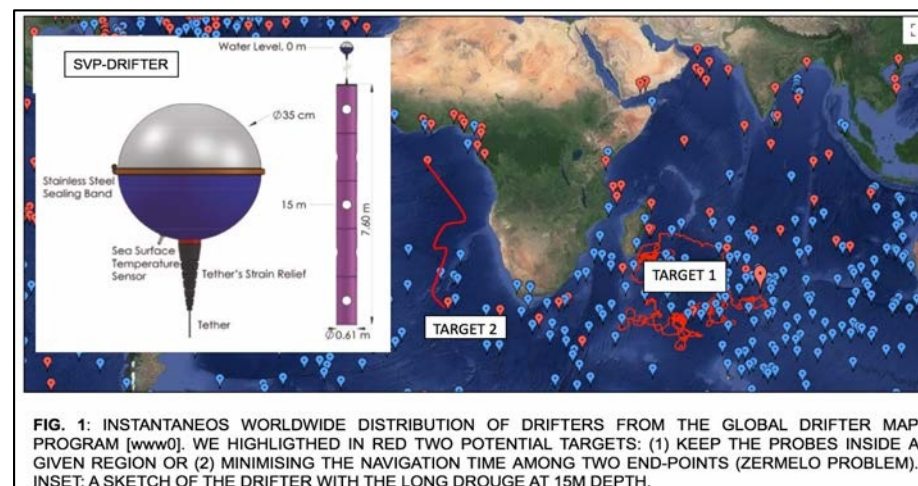
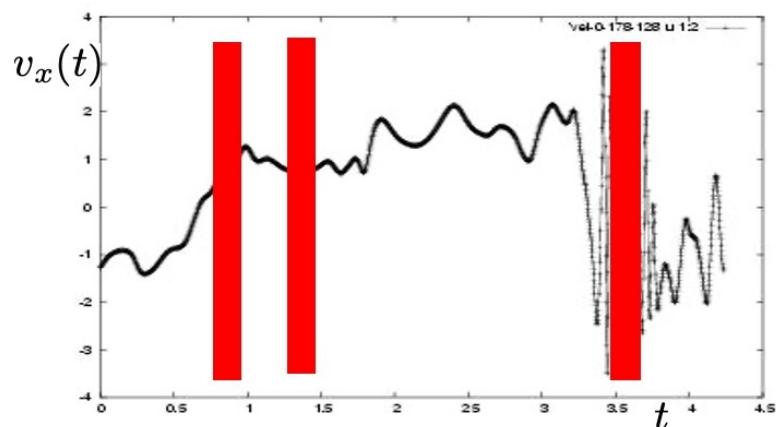
Viscosity?

Reynolds number?

Boundary
comditions?

Forcing properties?

Aspect ratio?



Machine-learning and equations-informed tools for generation
and augmentation of turbulent data.

Artificial Intelligence and the Uncertainty challenge in Fundamental Physics
Paris 2023

1. Short introduction to Eulerian Turbulence
2. Data-driven and Equation-Informed tools for Eulerian Turbulence:
 - a. Linear Principal Orthogonal Decomposition
 - b. Deterministic Generative Adversarial Networks
 - c. Diffusion Models
 - e. Nudging
 - f. Physics Informed NN

Entry #: 84174

Vortices within vortices:
hierarchical nature of vortex tubes in turbulence

Kai Bürger¹, Marc Treib¹, Rüdiger Westermann¹,
Suzanne Werner², Cristian C Lalescu³,
Alexander Szalay², Charles Meneveau⁴, Gregory L Eyink^{2,3,4}

¹ Informatik 15 (Computer Graphik & Visualisierung), Technische Universität München

² Department of Physics & Astronomy, The Johns Hopkins University

³ Department of Applied Mathematics & Statistics, The Johns Hopkins University

⁴ Department of Mechanical Engineering, The Johns Hopkins University

TURBULENCE OR TURBULENCES?

MASS X ACCELERATION = INTERNAL FORCES + EXTERNAL FORCES

$$\rho[\partial_t v + v \cdot \partial v] = -\partial p + \nu \Delta v + g\theta + F(B, B) + 2\Omega \times v + \hat{F}_{mech}$$

EULERIAN

$$\partial_t \theta + v \cdot \partial \theta = \chi \partial^2 \theta \leftarrow \text{TEMPERATURE}$$

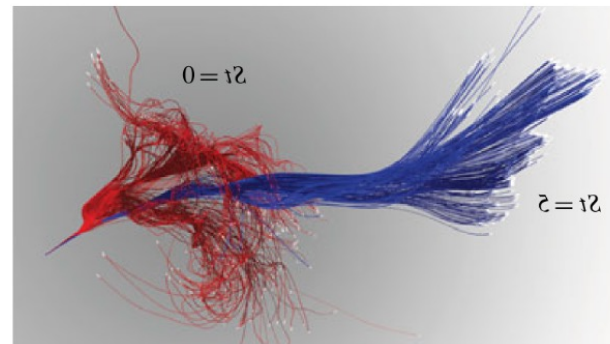
$$\partial_t B + v \cdot \partial B = B \cdot \partial v + \chi \partial^2 B \leftarrow \text{MAGNETIC FIELD}$$

$$\partial \cdot v = 0$$

+ BOUNDARY CONDITIONS: (2D, 3D, THIN/THICK LAYERS ETC...)

LAGRANGIAN

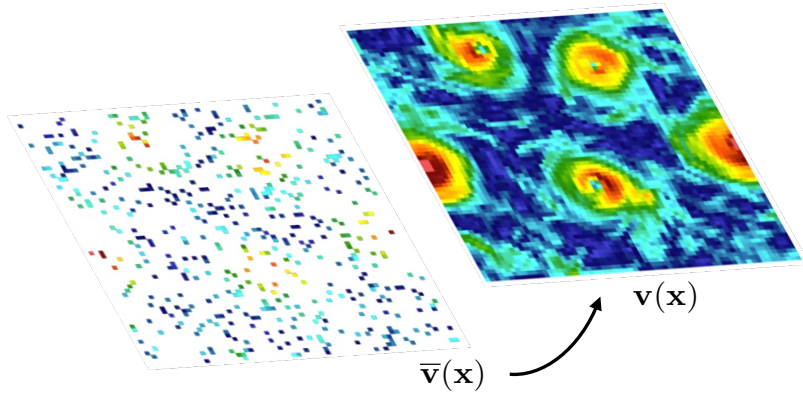
$$\dot{X}(t) = v(X(t), t)$$



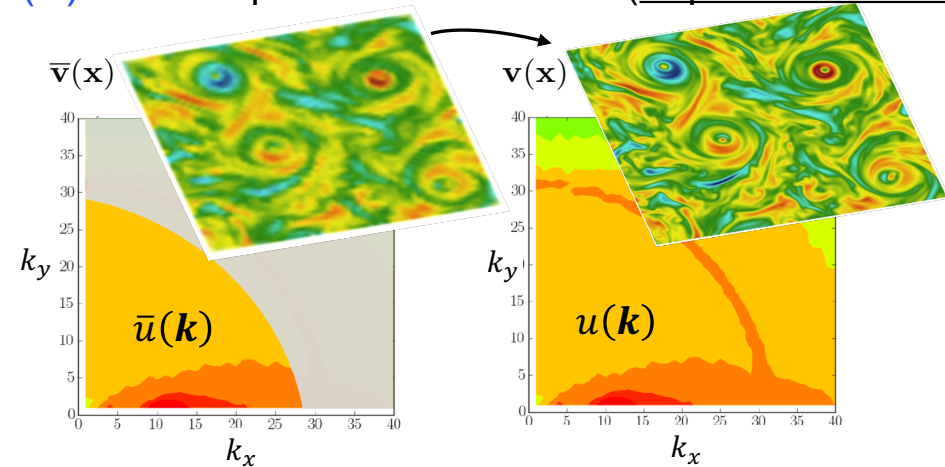
RECONSTRUCTION OF MISSING INFORMATION

FEATURES RANKING: QUALITY AND QUANTITY OF DATA

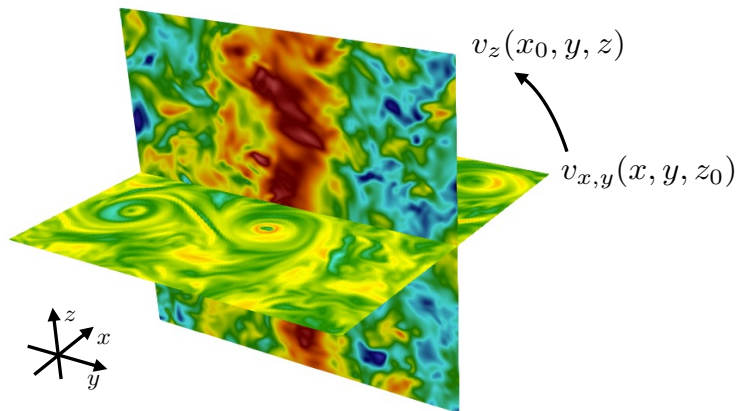
(i) Real-space Reconstruction (full state)



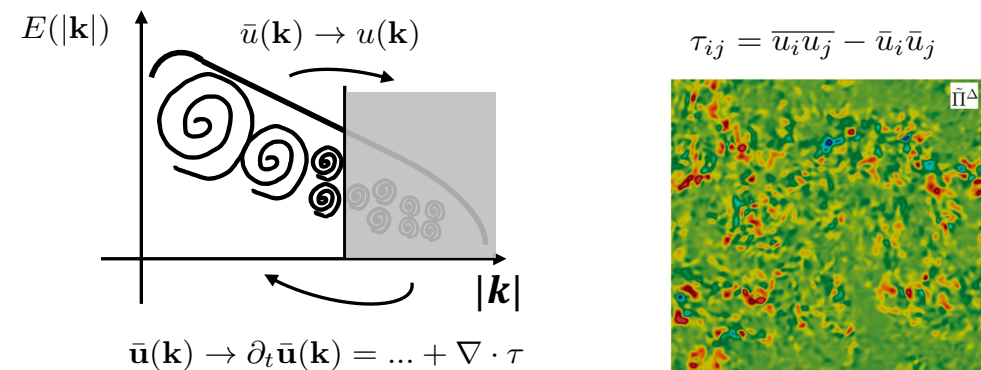
(iii) Fourier-space Reconstruction (Super Resolution)



(ii) Missing Physics (Inverse Problems)



(iv) Sub-Grid Modeling

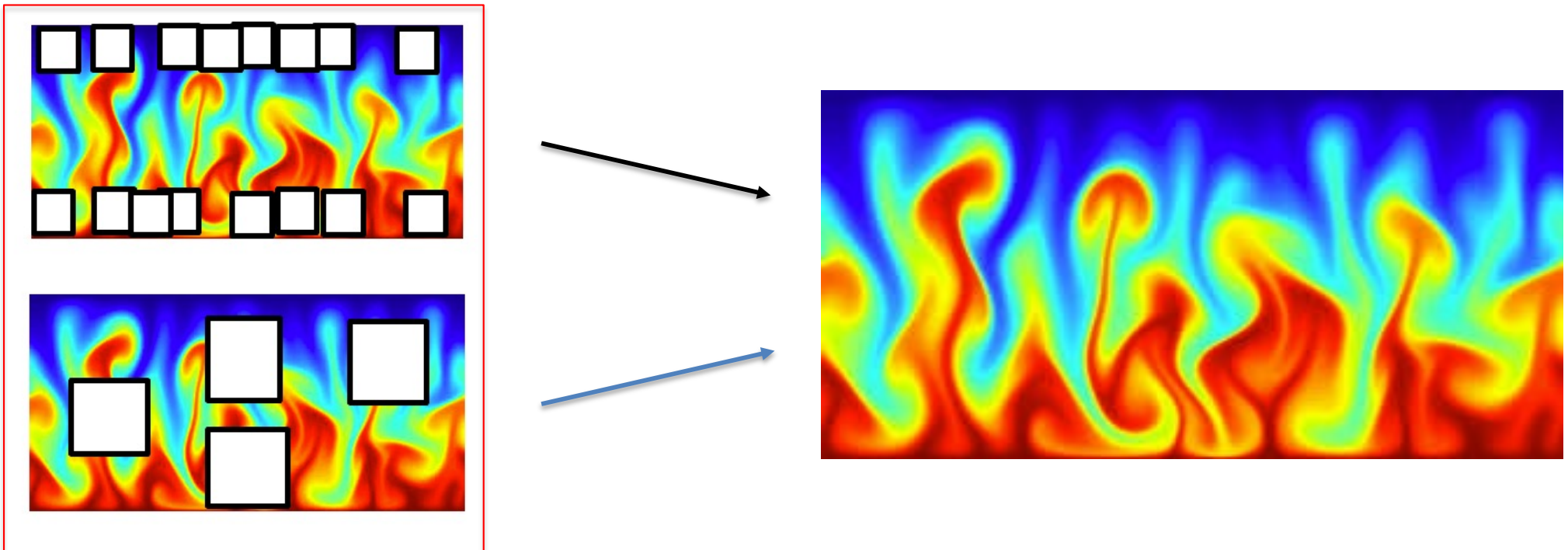


M. Buzzicotti. "Data reconstruction for complex flows using AI: recent progress, obstacles, and perspectives."
Europhysics Letters, EPL 142 23001 (2023).

WHY ?

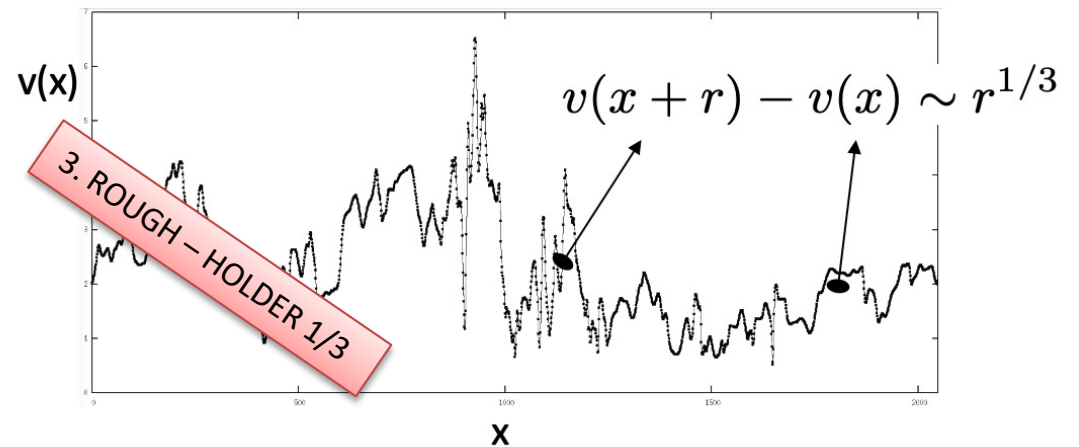
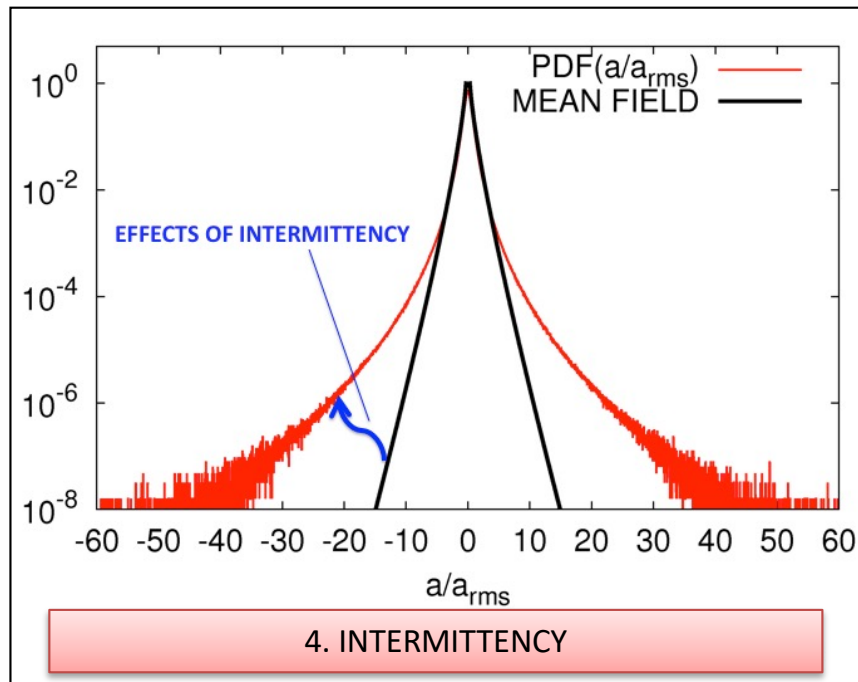
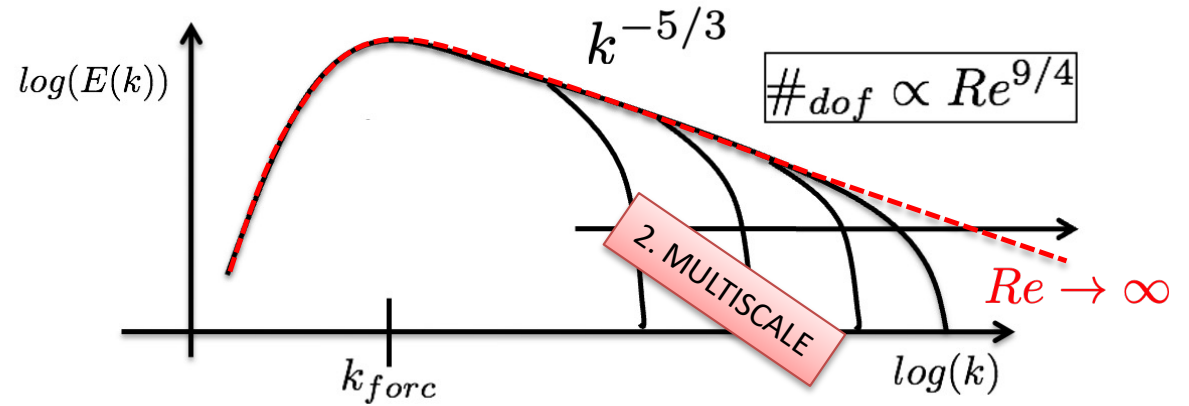
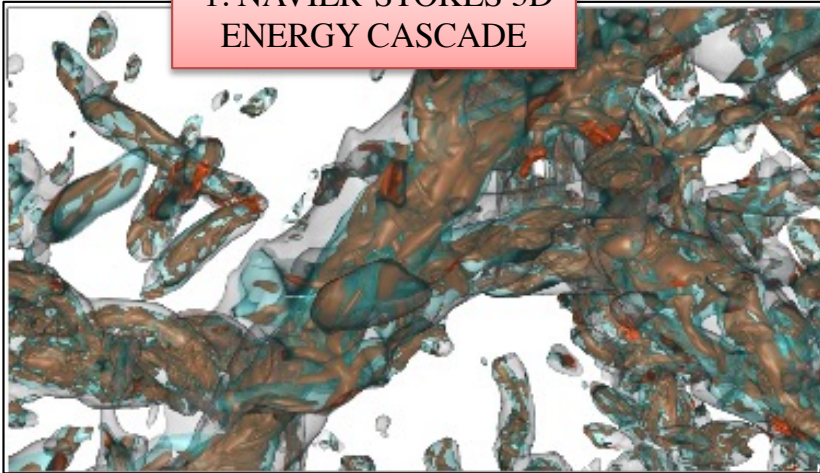
1. GENERATION OF MISSING INFORMATION (INPAINTING/SUPER-RESOLUTION) 2. FEATURES RANKING: WHAT IS THE BEST METRIC TO RECONSTRUCT TURBULENT DATA?

- IT IS MORE DIFFICULT TO RECONSTRUCT SPATIAL OR TEMPORAL DATA?
- HOW MANY DATA/VARIABLES YOU NEED TO SUPPLY FOR PERFECT RECONSTRUCTION (SYNCHRONIZATION-TO-DATA)?
- CAN YOU INFER VELOCITY FIELDS FROM TEMPERATURE SNAPSHOTS AND/OR VICEVERSA?
- IS IT BETTER TO PROVIDE INFORMATION FROM BOUNDARIES OR BULK?
- FROM LARGE OR SMALL SCALES?
- **DO WE NEED (IS IT USEFUL) TO KNOW THE EQUATIONS?**
- **HOW TO COMPARE EQUATIONS-BASED AND EQUATIONS-FREE MODELS?**



WHY IS IT TOUGH?

1. NAVIER-STOKES 3D ENERGY CASCADE



1. OUT-OF-EQUILIBRIUM (NO GIBBS MEASURE)
2. MANY-BODY (INFINITE DEGREES OF FREEDOM)
3. NON-DIFFERENTIABLE FIELDS (HOLDER 1/3)
4. STRONGLY-NON GAUSSIAN

WHY IS IT TOUGH?

1. NAVIER-STOKES 3D
ENERGY CASCADE

FIRST EXASCALE COMPUTATION
WORLD-RECORD

76th Annual Meeting of the Division of Fluid Dynamics

Sunday–Tuesday, November 19–21, 2023; Washington, DC

Session T02: Turbulence: DNS

4:25 PM–5:56 PM, Monday, November 20, 2023

Room: Ballroom B

Chair: Robert Moser, University of Texas at Austin

Abstract: T02.00005 : Turbulence simulations at grid resolution up to 32768^3 enabled by Exascale computing*

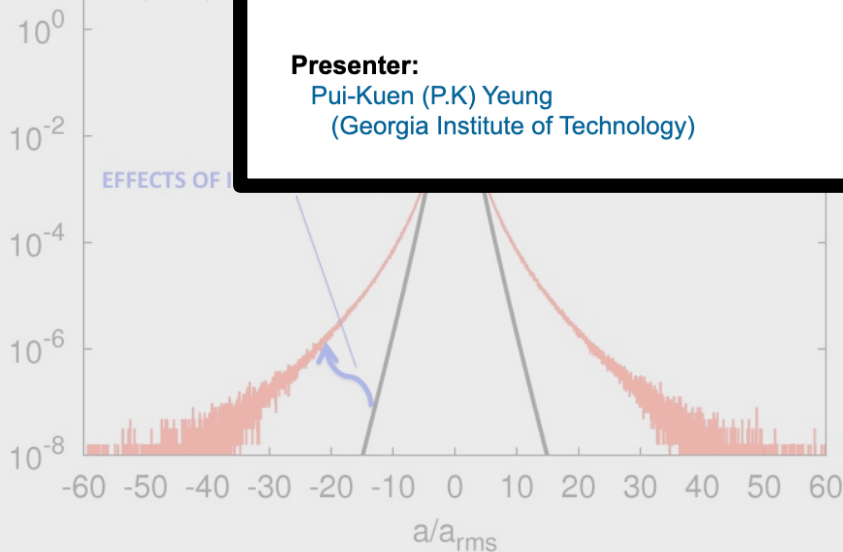
5:17 PM–5:30 PM

Presenter:

Pui-Kuen (P.K.) Yeung
(Georgia Institute of Technology)

$32768^3 \sim 35$ TRILLION GRID POINT
1 CONF ~ 1 PETABYTE

FEATURES RANKING!!!



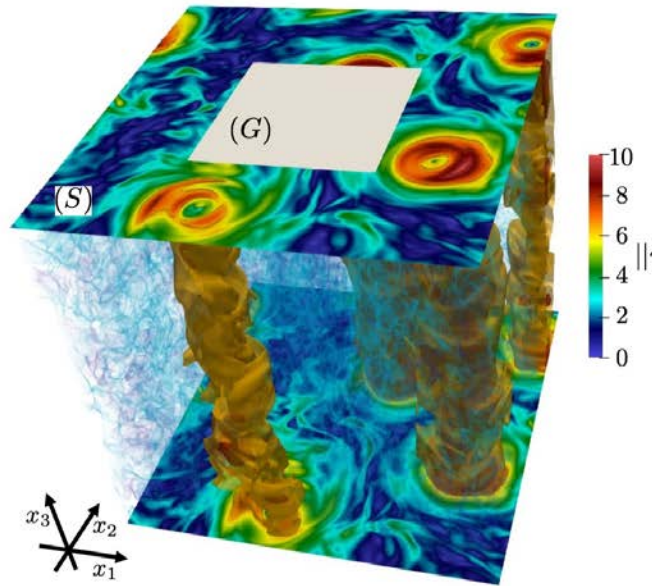
4. INTERMITTENCY



1. OUT-OF-EQUILIBRIUM (NO GIBBS MEASURE)
2. MANY-BODY (INFINITE DEGREES OF FREEDOM)
3. NON-DIFFERENTIABLE FIELDS (HOLDER 1/3)
4. STRONGLY-NON GAUSSIAN

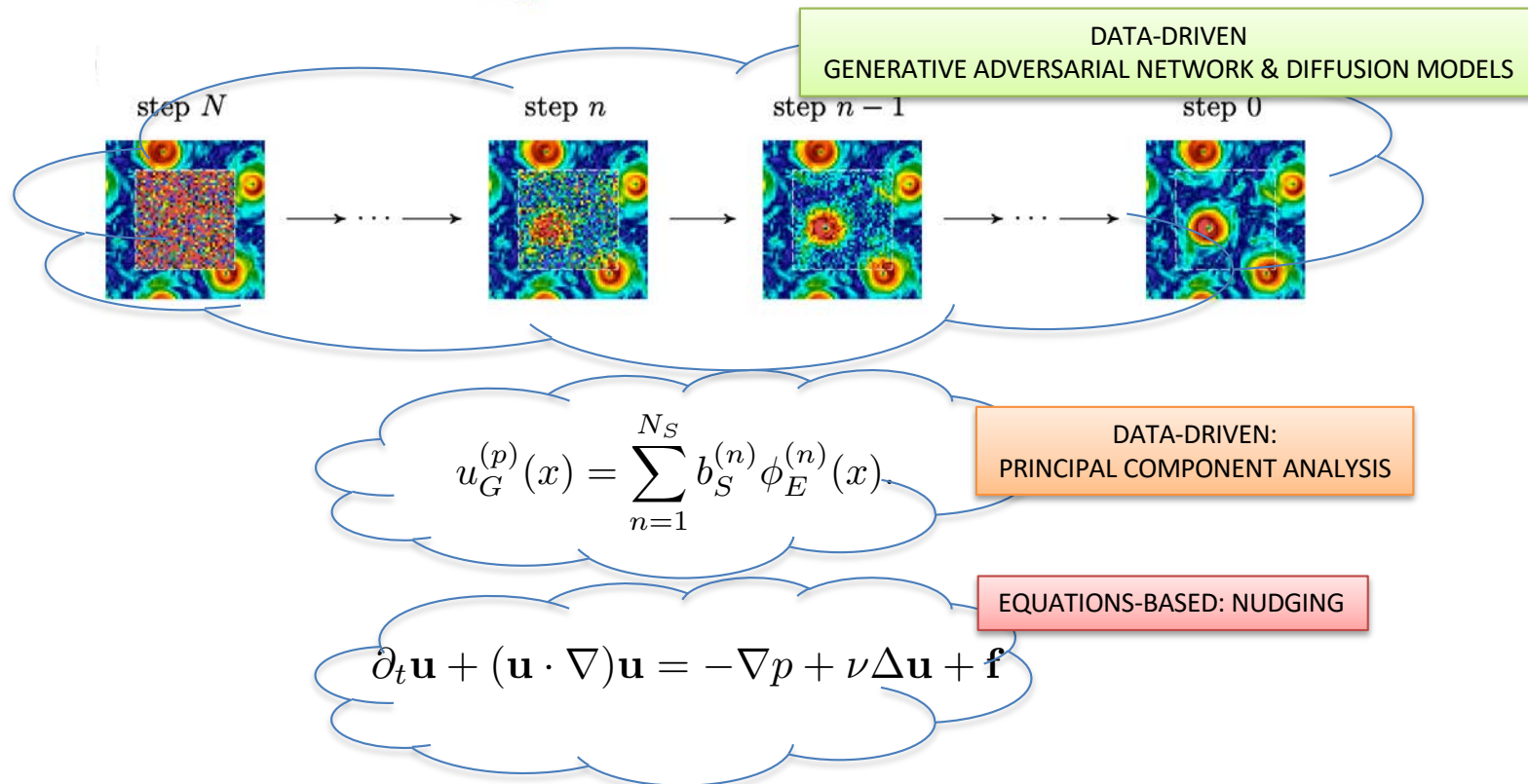
grid resolution: 1024^3

Coherent Structures and Extreme Events in Rotating Multiphase Turbulent Flows.
LB, F. Bonaccorso, I. M. Mazzitelli, et al. Phys. Rev. X **6**, 041036 – 2016



3D TURBULENCE
UNDER ROTATION

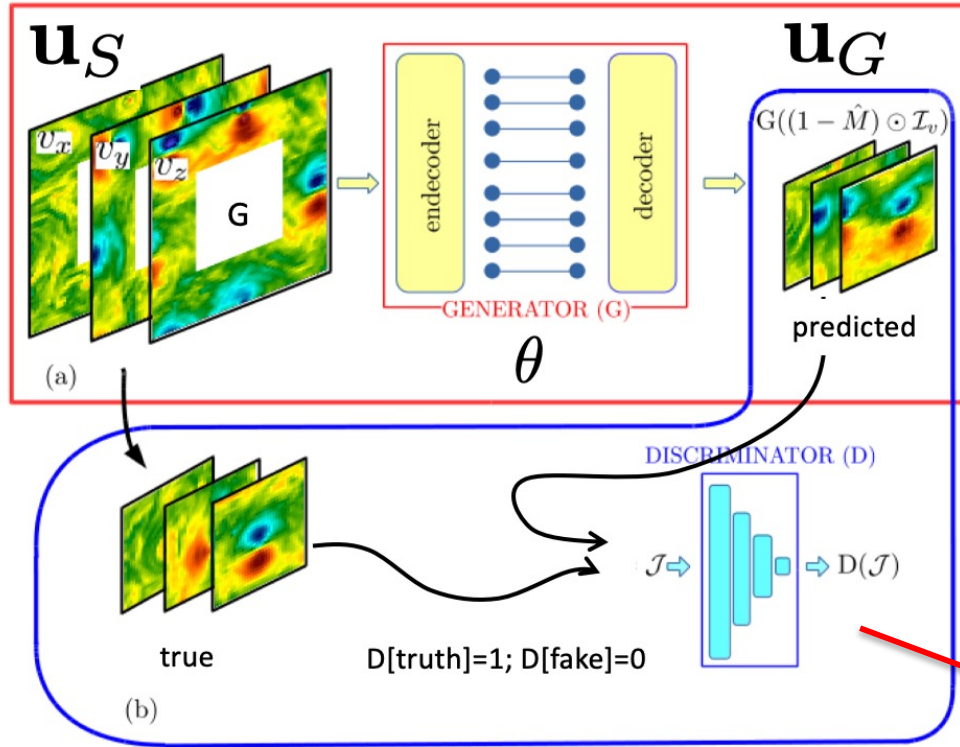
MOCK SATELLITE
MEASUREMENTS



Context Encoder: features learning by inpainting. D. Pathak, P. Krahenbuhl, J. Donahue, T. Darrel, A. Efros. Proceed. of the IEEE Conf. on Computer Vision and Pattern Recognition, 2536, (2016)

Reconstruction of turbulent data with deep generative models for semantic inpainting from TURB-Rot database. M. Buzzicotti, F. Bonaccorso, P. Clark Di Leoni, and L. B. Phys. Rev. Fluids 6, 050503, May 2021

NONLINEAR GENERATIVE ADVERSARIAL NETWORK: CONTEXT ENCODER (ACTOR-CRITIC)



MINIMIZE:

$$\mathcal{L}_{GEN} = (1 - \lambda_{adv})\mathcal{L}_{MSE} + \lambda_{adv}\mathcal{L}_{adv},$$

$$\mathcal{L}_{MSE} = \left\langle \frac{1}{A(I)} \int_I \|\mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x})\|^2 d\mathbf{x} \right\rangle$$

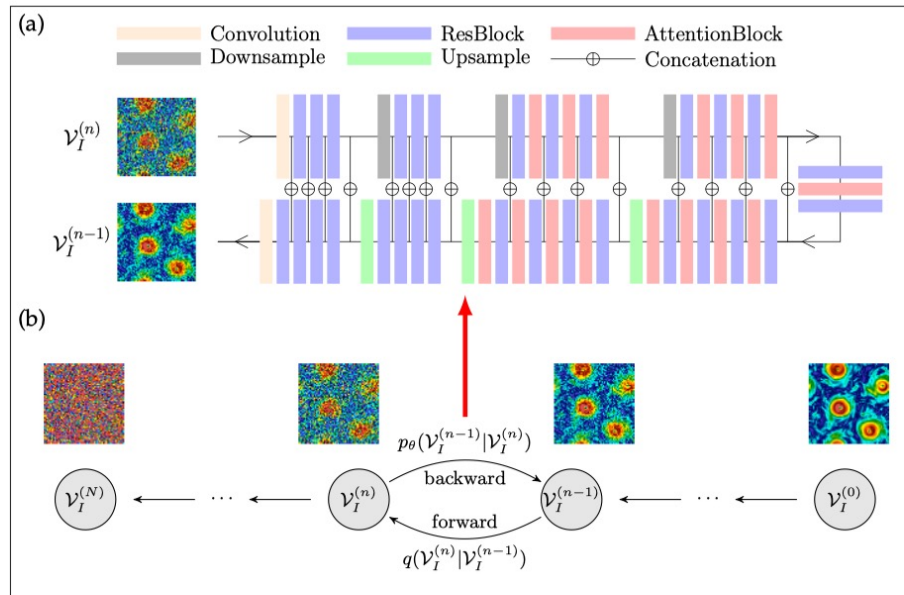
$$\begin{aligned} \mathcal{L}_{adv} &= \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle \\ &= \int p(\mathbf{u}_S) \log[1 - D(GEN(\mathbf{u}_S))] d\mathbf{u}_S \end{aligned}$$

MAXIMIZE:

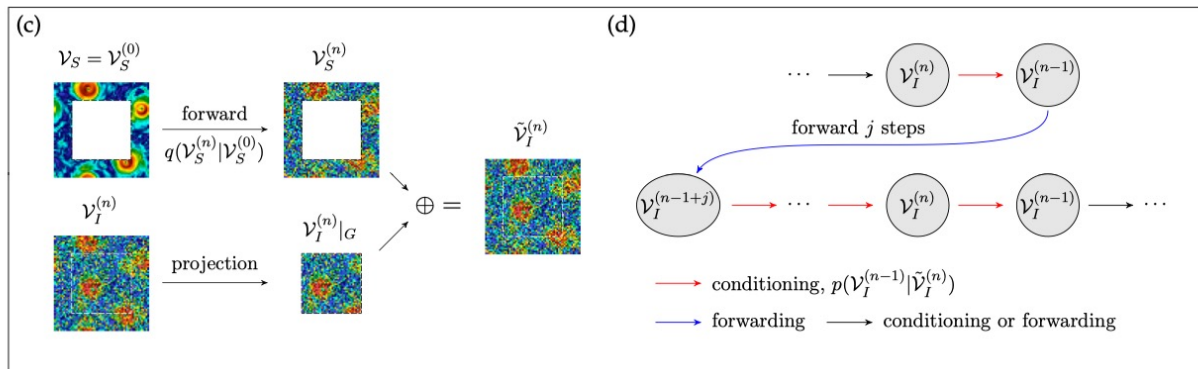
$$\begin{aligned} \mathcal{L}_{DIS} &= \langle \log(D(\mathbf{u}_G^{(t)})) \rangle + \langle \log(1 - D(\mathbf{u}_G^{(p)})) \rangle \\ &= \int [p_t(\mathbf{u}_G) \log(D(\mathbf{u}_G)) + p_p(\mathbf{u}_G) \log(1 - D(\mathbf{u}_G))] d\mathbf{u}_G \end{aligned}$$

$$KL(p_t \parallel p_p) = \int_{-\infty}^{\infty} p_t(x) \log \left(\frac{p_t(x)}{p_p(x)} \right) dx$$

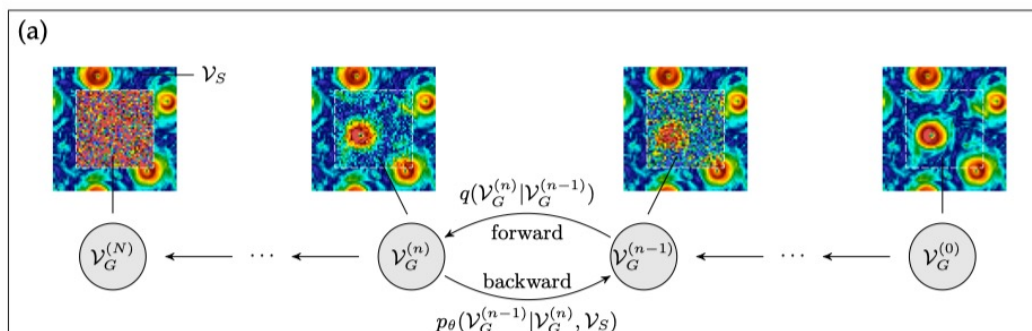
KULLBACK-LEIBLER DISTANCE



1. DIFFUSION MODELS UNCONDITIONAL GENERATION OUT OF I.I.D. NOISE



RePAINT: UNCONDITIONAL INPAINTING OUT OF I.I.D. NOISE



PALETTE: CONDITIONAL INPAINTING OUT OF I.I.D. NOISE

LINEAR: EXTENDED-PRINCIPAL ORTHOGONAL DECOMPOSITION (EPOD)

$$R_S(x, y) = \langle u(x)u(y) \rangle$$

$$\int_{\Omega} R_S(x, y) \phi_S^{(n)}(y) dy = \sigma_n \phi_S^{(n)}(x),$$

$$u_S(x) = \sum_{n=1}^{N_S} b_S^{(n)} \phi_S^{(n)}(x),$$

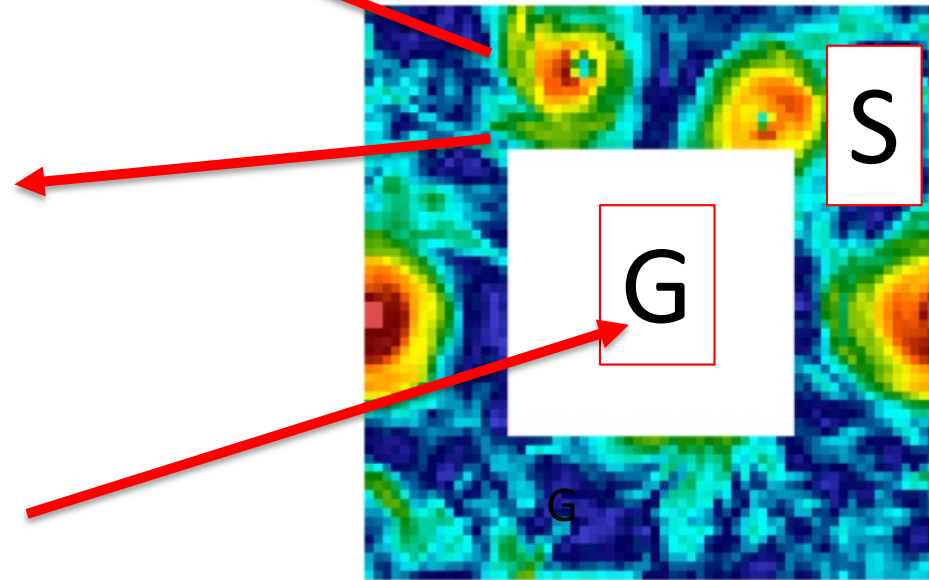
$$\phi_S^{(n)}(x) = \langle b_S^{(n)} u_S(x) \rangle / \sigma_n.$$



TRAINING

$$\phi_E^{(n)}(x) = \langle b_S^{(n)} u_G(x) \rangle / \sigma_n.$$

$$\text{MSE} = \int_I \| \mathbf{u}_G^{(p)}(\mathbf{x}) - \mathbf{u}_G^{(t)}(\mathbf{x}) \|^2 d\mathbf{x}$$

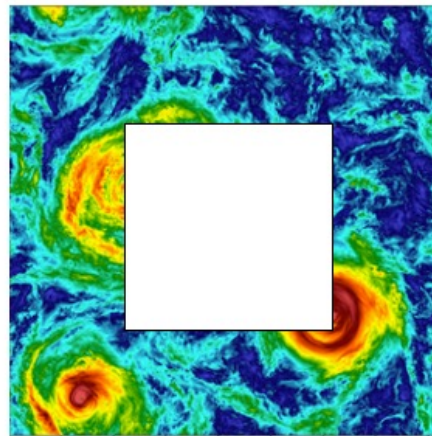


RECONSTRUCTION

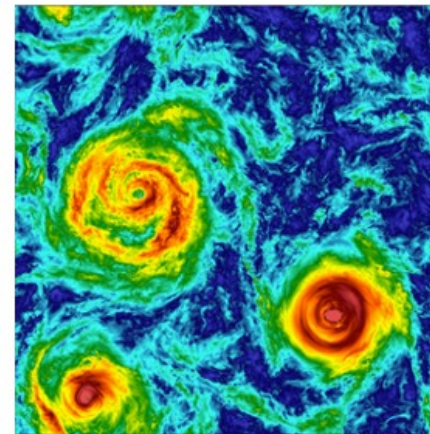
$$u_G^{(p)}(x) = \sum_{n=1}^{N_S} b_S^{(n)} \phi_E^{(n)}(x).$$

NUDGING: AN EQUATION-INFORMED UNBIASED TOOL TO ASSIMILATE AND RECONSTRUCT TURBULENCE DATA/PHYSICS BY ADDING A DRAG TERM AGAINST PARTIAL FIELD MEASUREMENTS

C.C. Lalescu, C. Meneveau and G.L. Eyink. Synchronization of Chaos in Fully Developed Turbulence. Phys. Rev. Lett. 110, 084102 (2013)
 A.Farhat, E. Lunasin, and E.S. Titi. Abridged Continuous Data Assimilation for the 2d Navier-Stokes Equations Utilizing Measurements of Only One Component of the Velocity Field. J. Math. Fluid Mech. 18(1), 1 (2016)



???????



FULLY PHYSICS COMPLIANT

NEED HUGE COMPUTATIONAL RESOURCES

$$\mathbf{v}_N = G[\mathbf{v}_{true}]$$

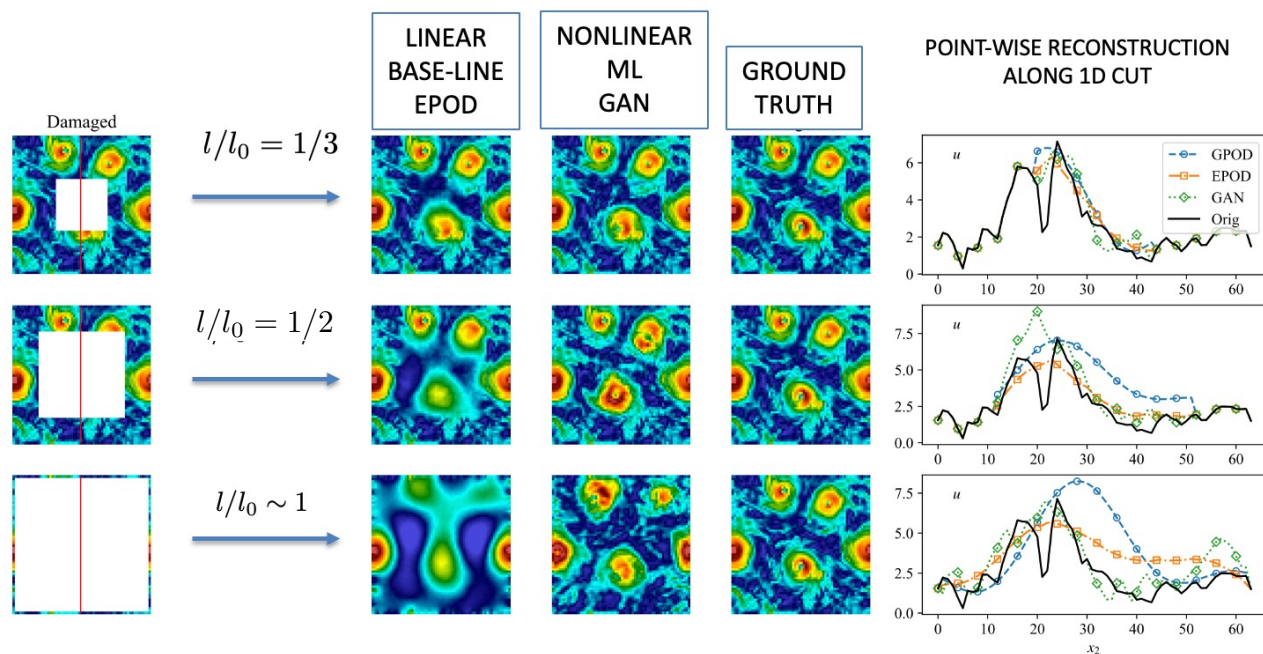
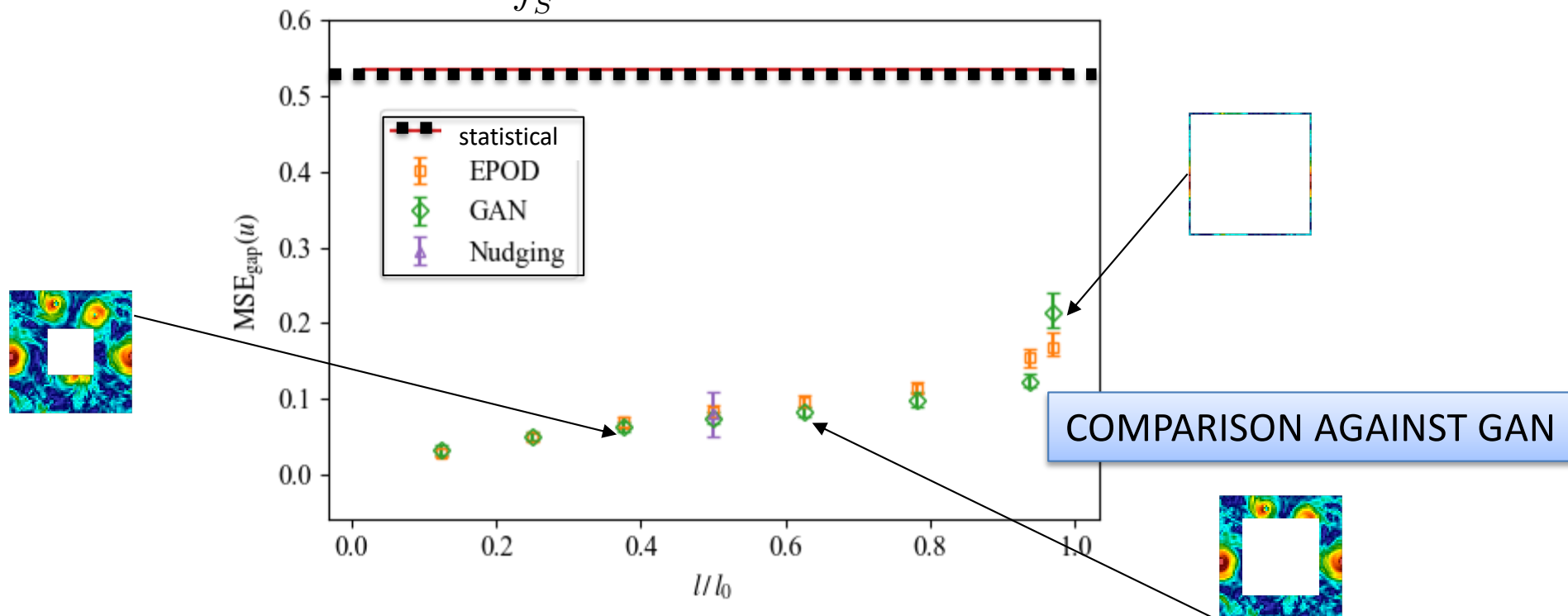
$$\mathbf{v}_{true}$$

$$\begin{cases} \partial_t \mathbf{v} + \mathbf{v} \cdot \partial_{\mathbf{x}} \mathbf{v} + \partial_{\mathbf{x}} P - \nu \Delta \mathbf{v} = 2\mathbf{v} \times \boldsymbol{\Omega} + \mathcal{S}\mathbf{v} + \alpha g \hat{\mathbf{z}} T + \mathcal{F} - N(\mathbf{v}_N - \mathbf{v}) \\ \partial_x \mathbf{v} = 0 \end{cases}$$

NO NEED TO TRAIN!! NAVIER AND STOKES DID THE JOB FOR YOU: ONE CONF IS ENOUGH

Patricio Clark Di Leoni, Andrea Mazzino, and L.B. Synchronization to Big Data:
 Nudging the Navier-Stokes Equations for Data Assimilation of Turbulent Flows Phys. Rev. X 10, 011023 (2020)

$$\text{MSE} = \left\langle \int_S d\mathbf{x} (u_{true}(\mathbf{x}) - u_{pred}(\mathbf{x}, \theta))^2 \right\rangle$$



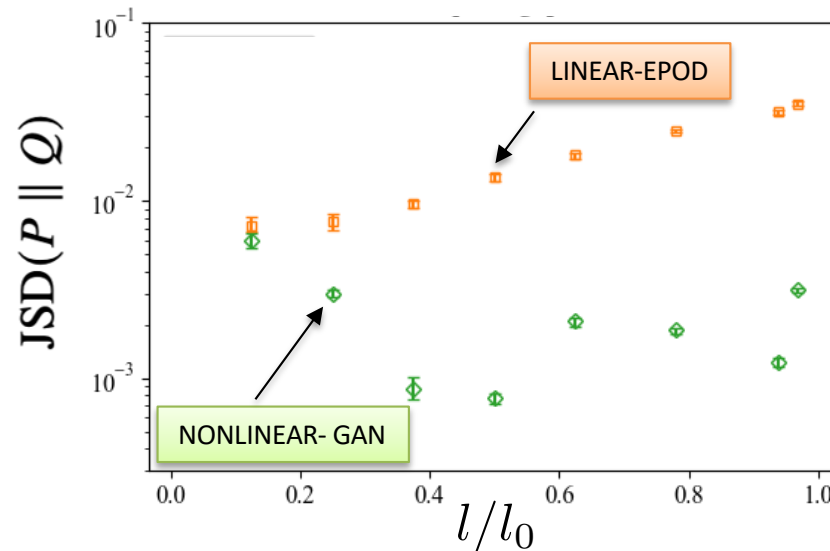
KULLBACK-LEIBLER

$$D(P \parallel Q) = \int_{-\infty}^{\infty} P(x) \log \left(\frac{P(x)}{Q(x)} \right) dx$$

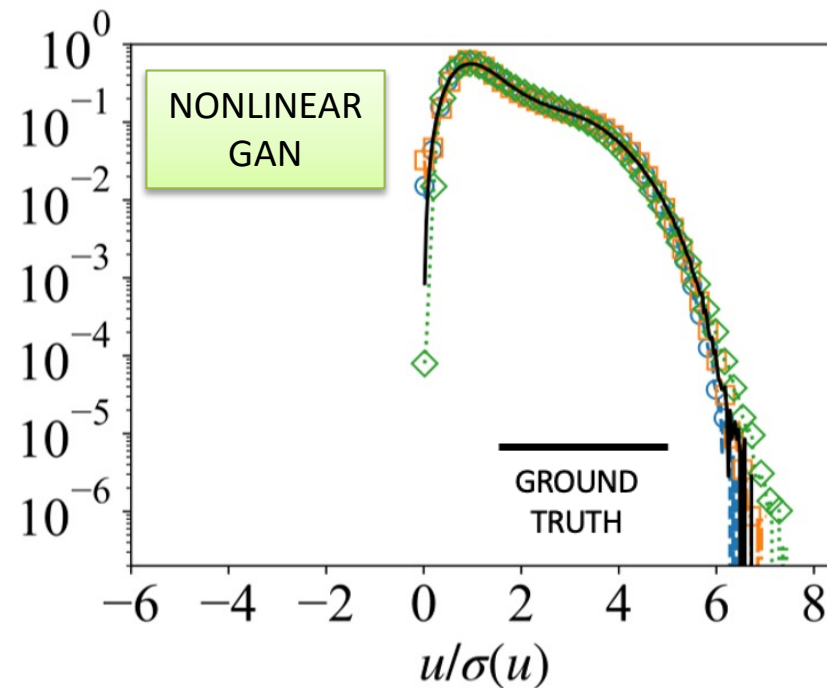
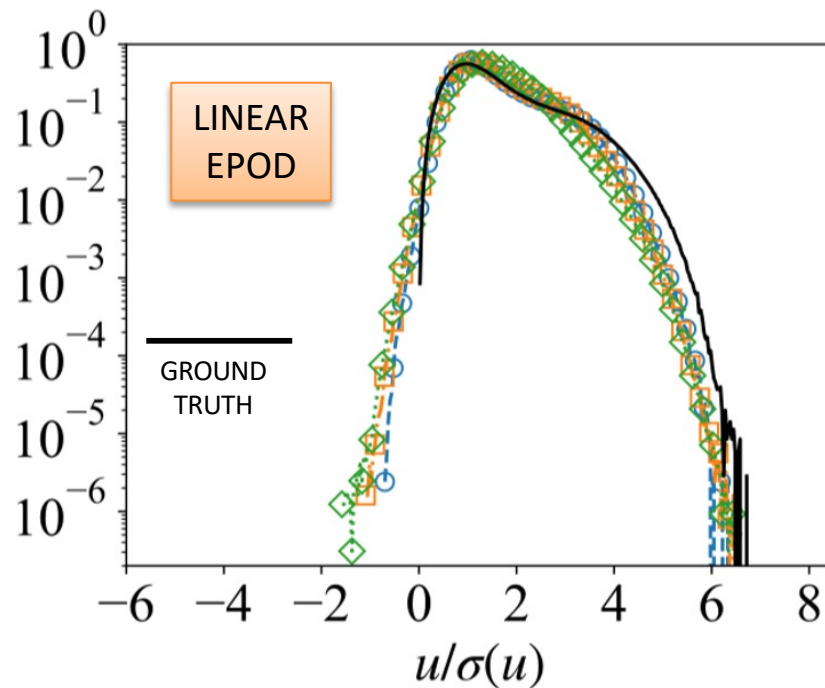
$$M = \frac{1}{2}(P + Q)$$

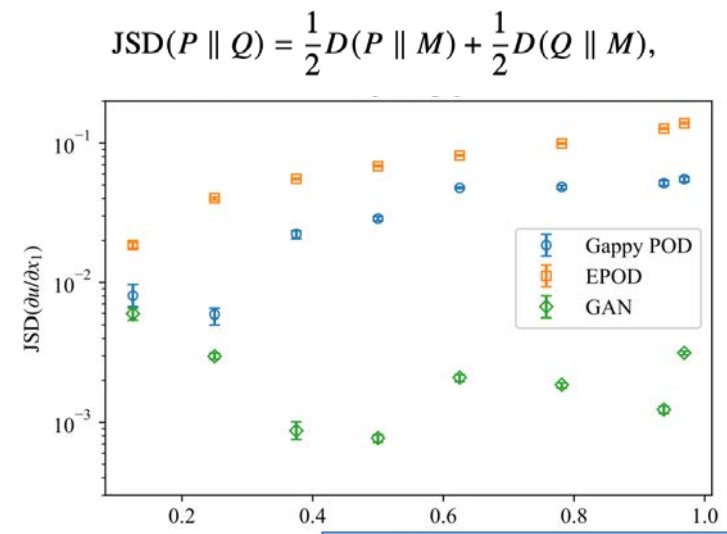
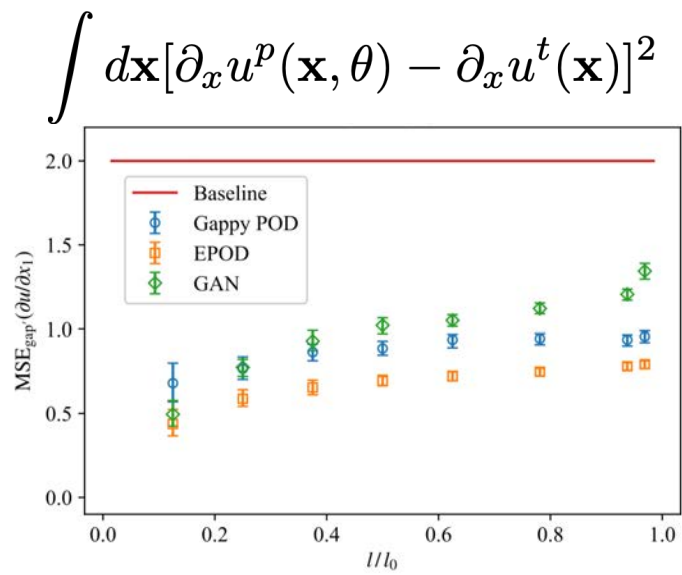
JENSEN-SHANNON

$$JSD(P \parallel Q) = \frac{1}{2}D(P \parallel M) + \frac{1}{2}D(Q \parallel M),$$



COMPARISON AGAINST GAN

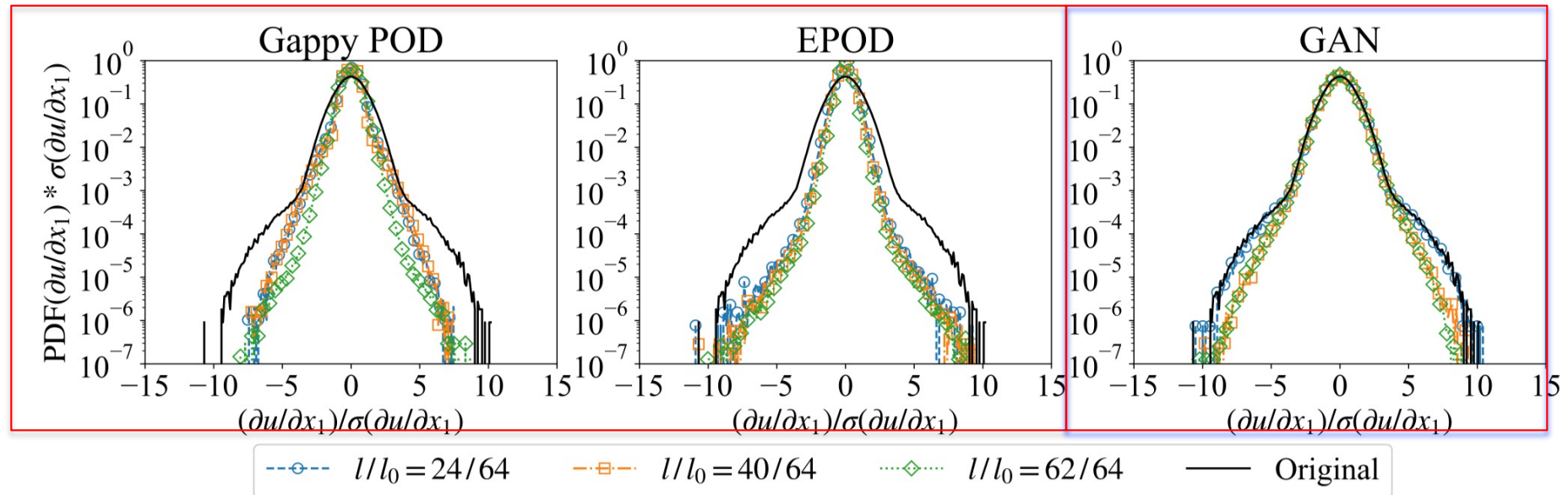


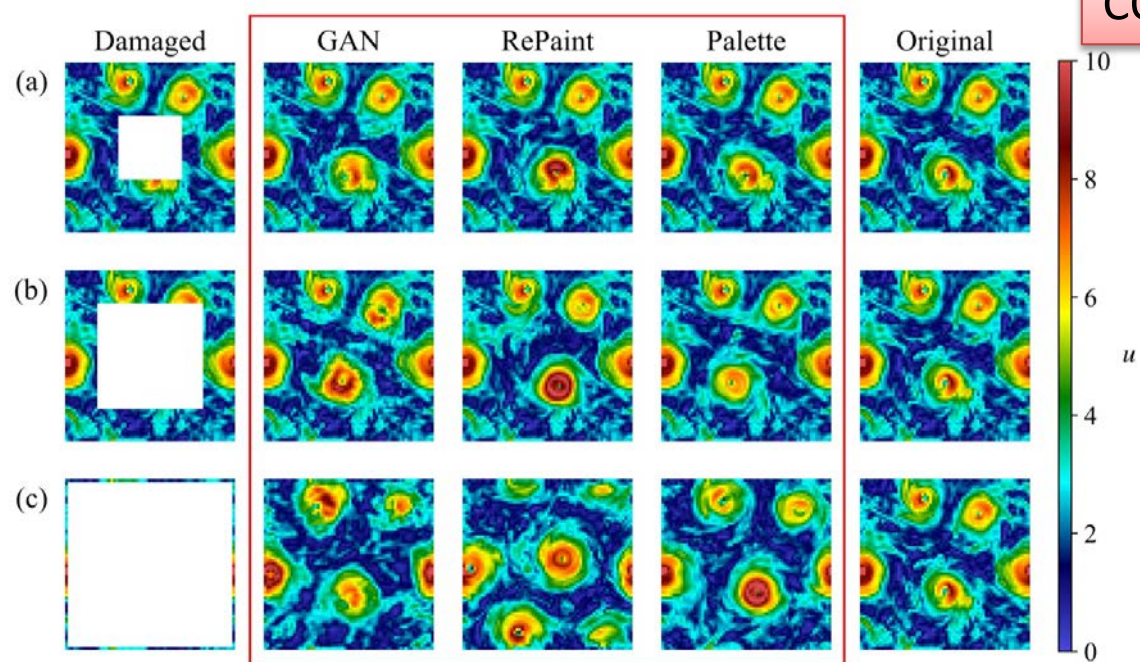
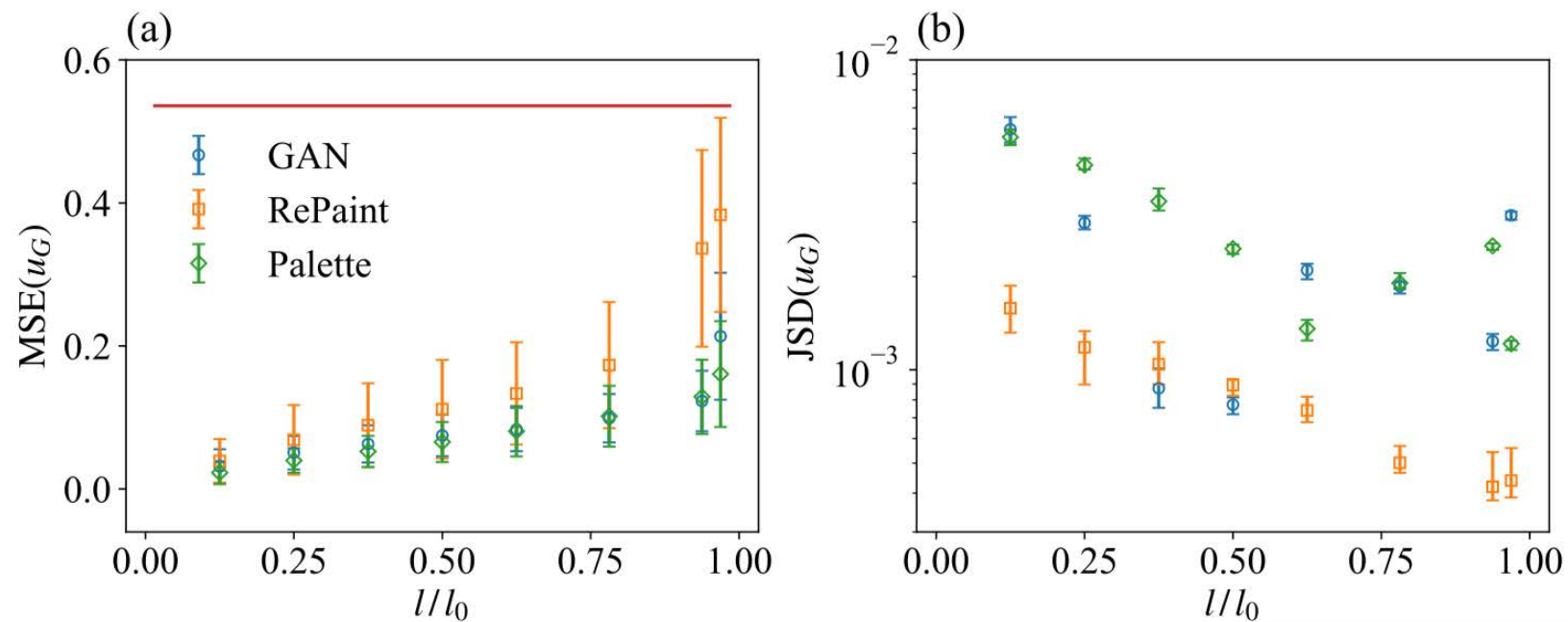


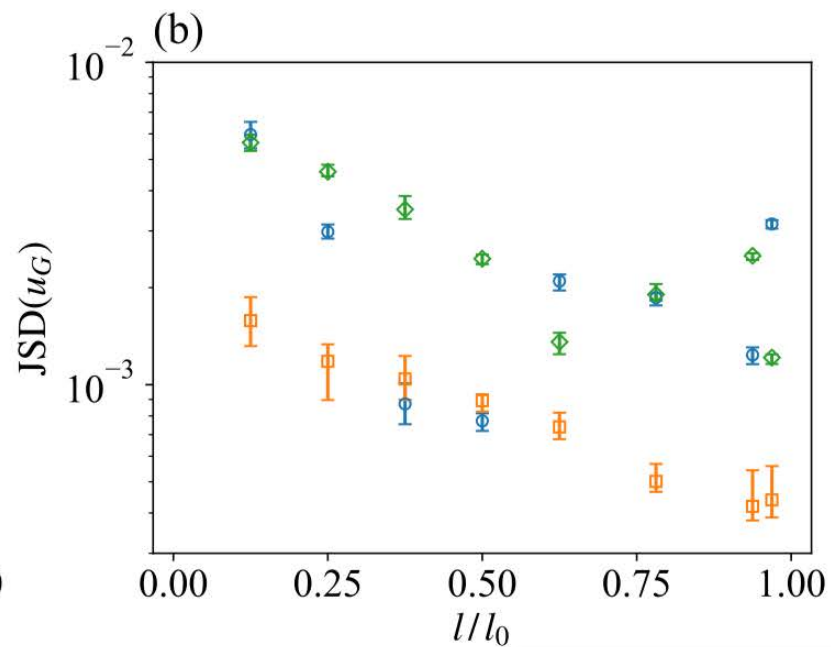
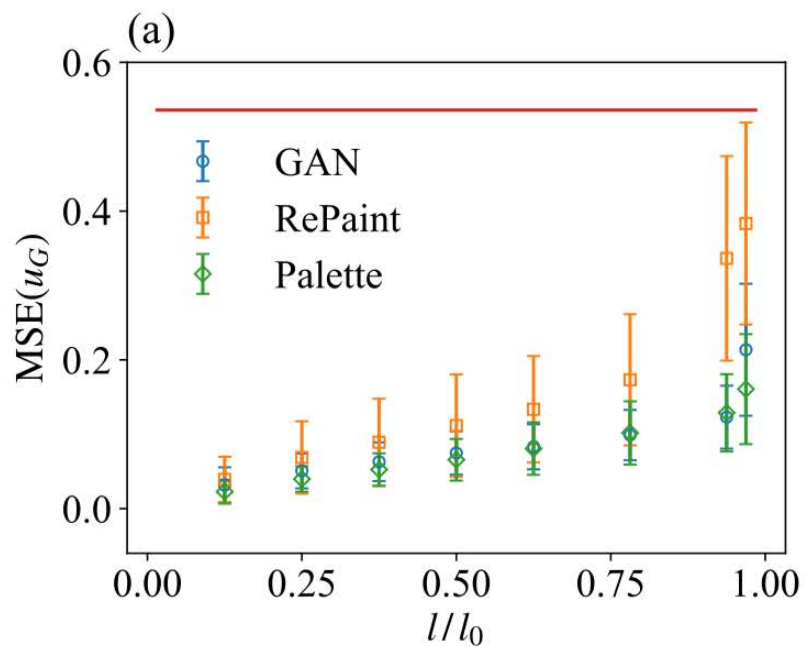
COMPARISON AGAINST GAN

LINEAR GAPPY-POD & EPOD

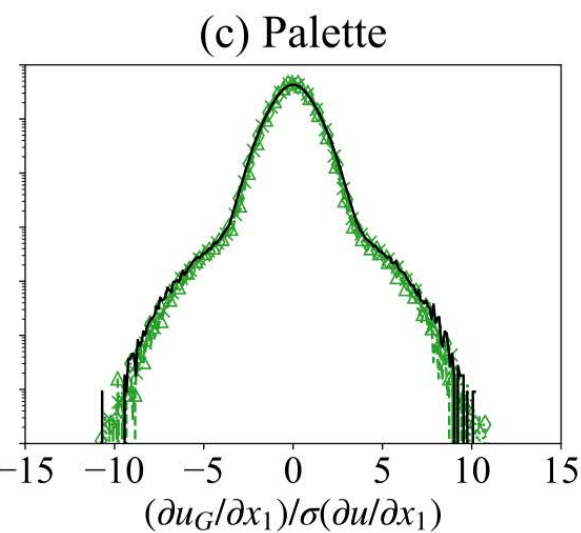
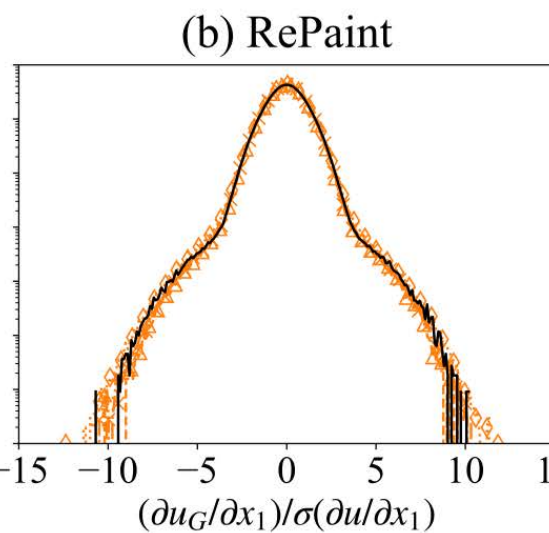
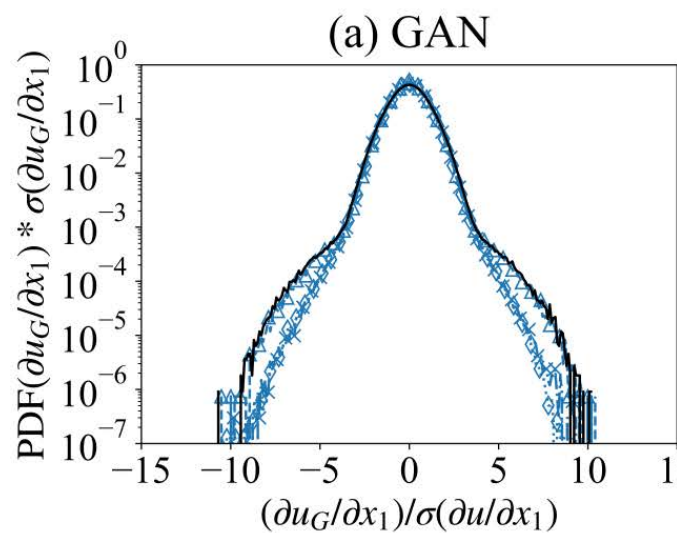
NONLINEAR GAN



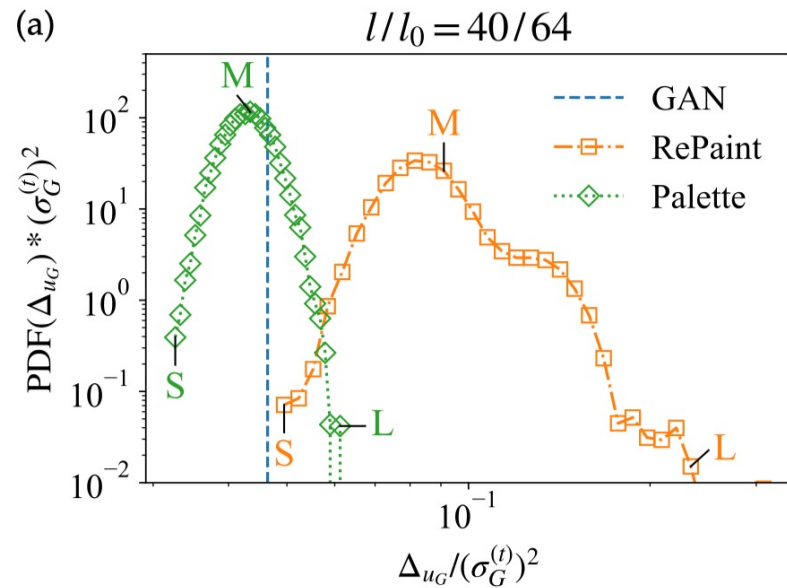
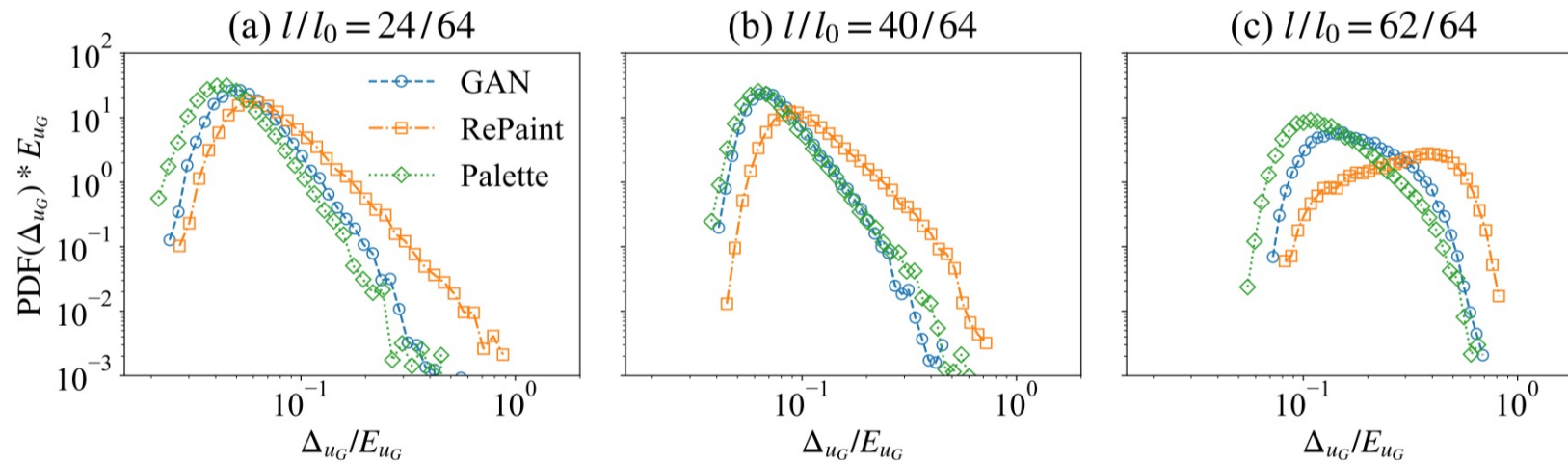
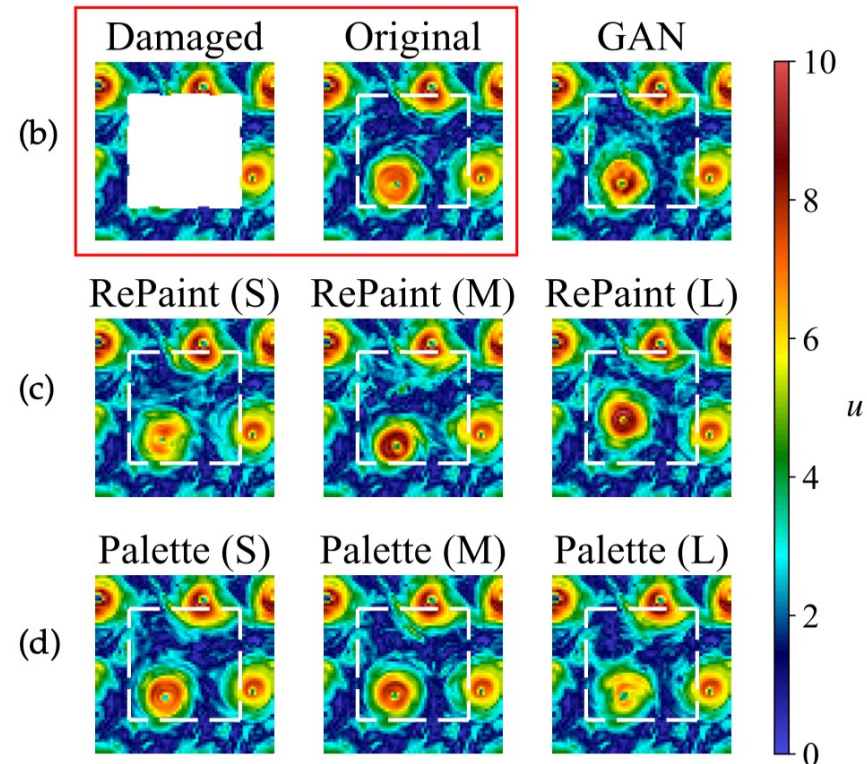




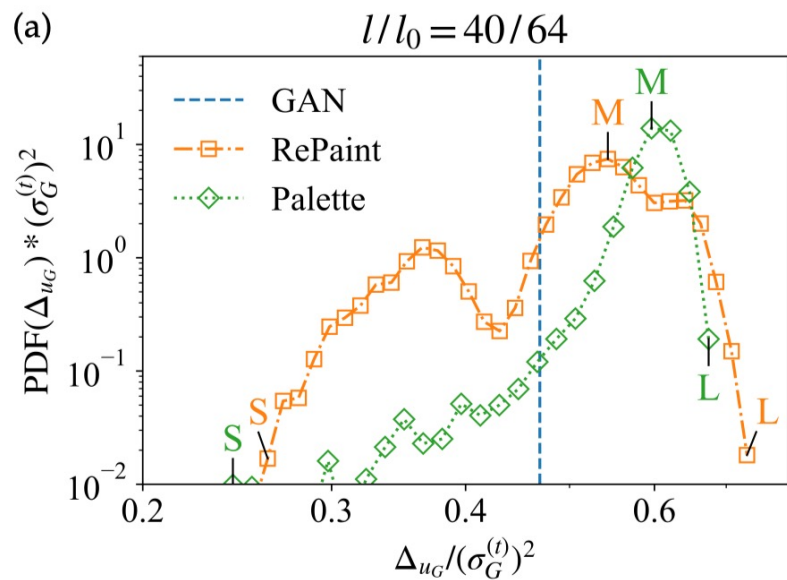
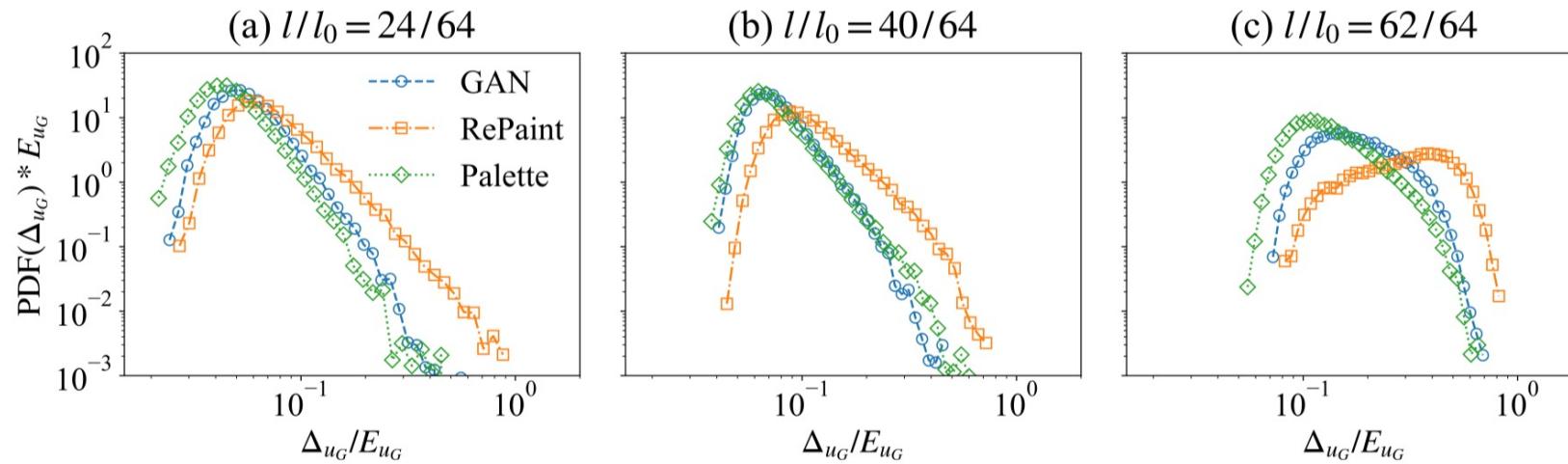
COMPARISON GAN/DM



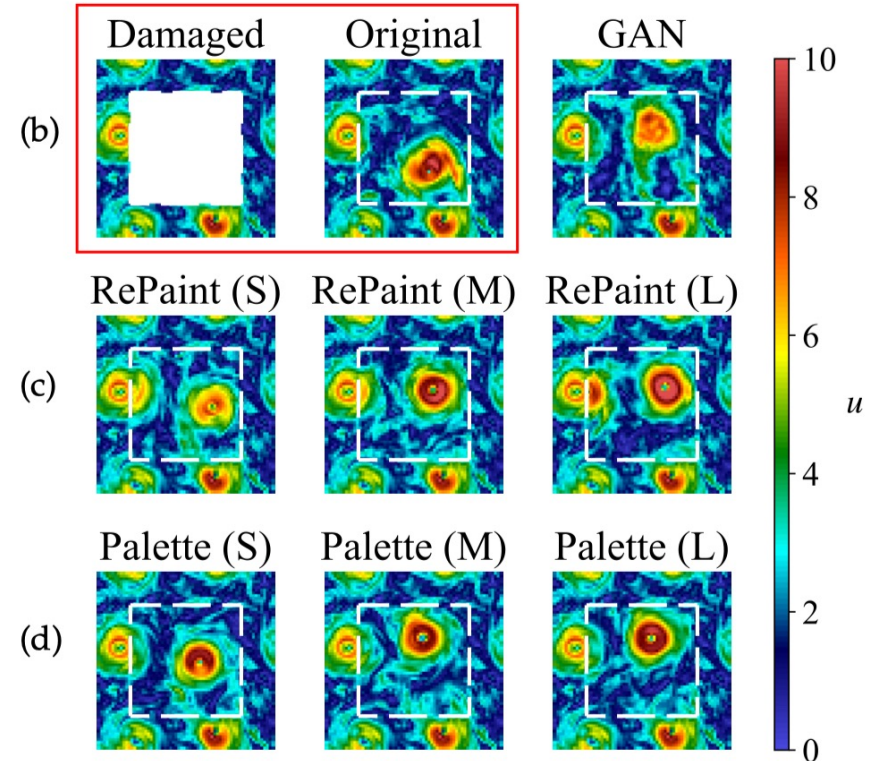
PDF OF L2 ERROR – SINGLE IMAGE

UNCERTAINTY
QUANTIFICATION

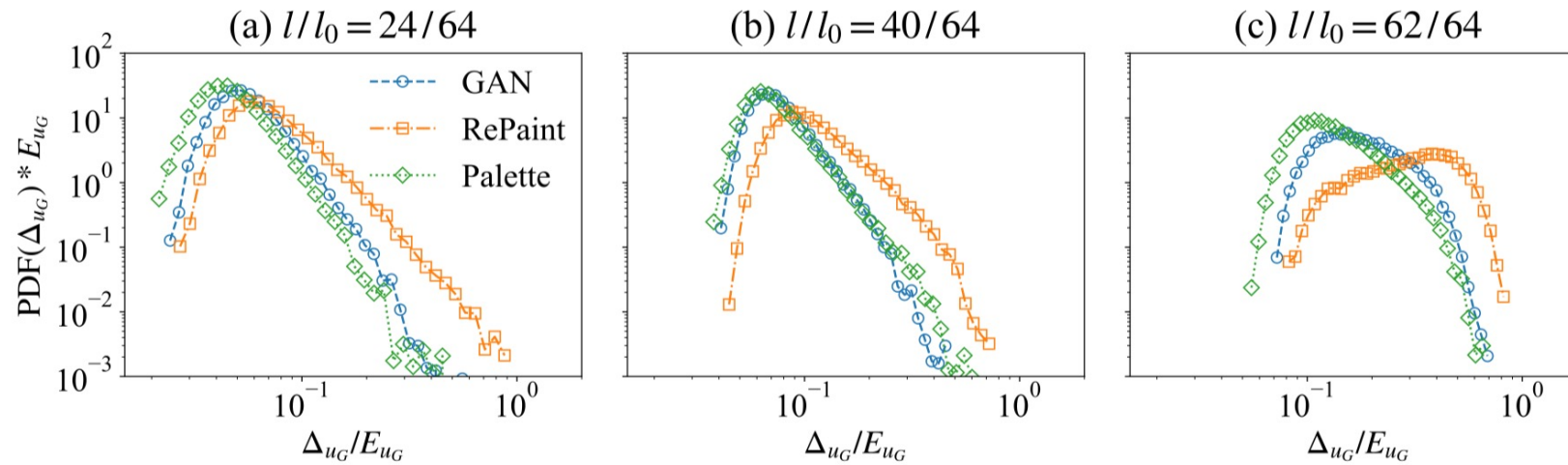
PDF OF L2 ERROR – SINGLE IMAGE



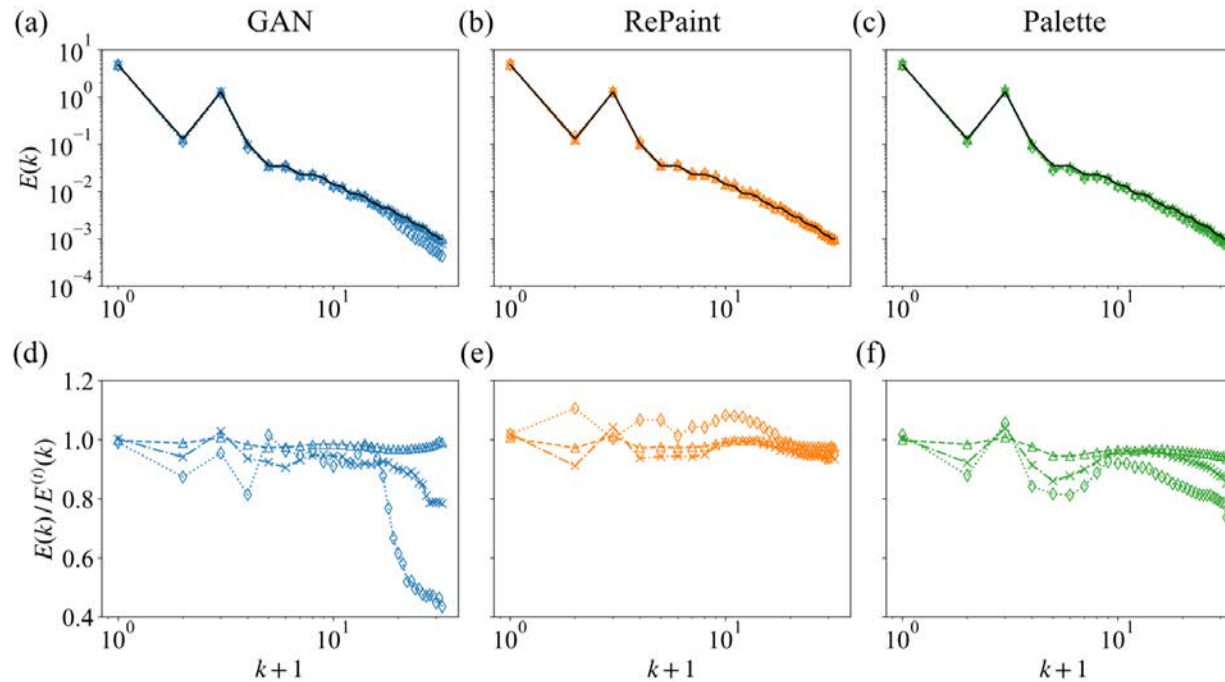
UNCERTAINTY
QUANTIFICATION



PDF OF L2 ERROR – SINGLE IMAGE

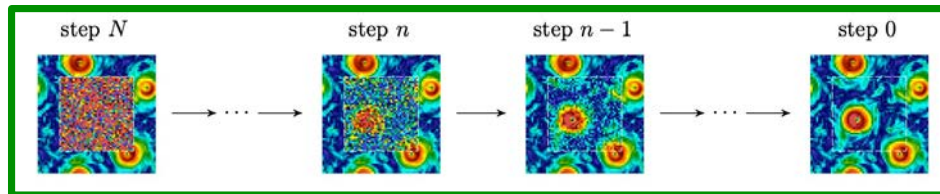
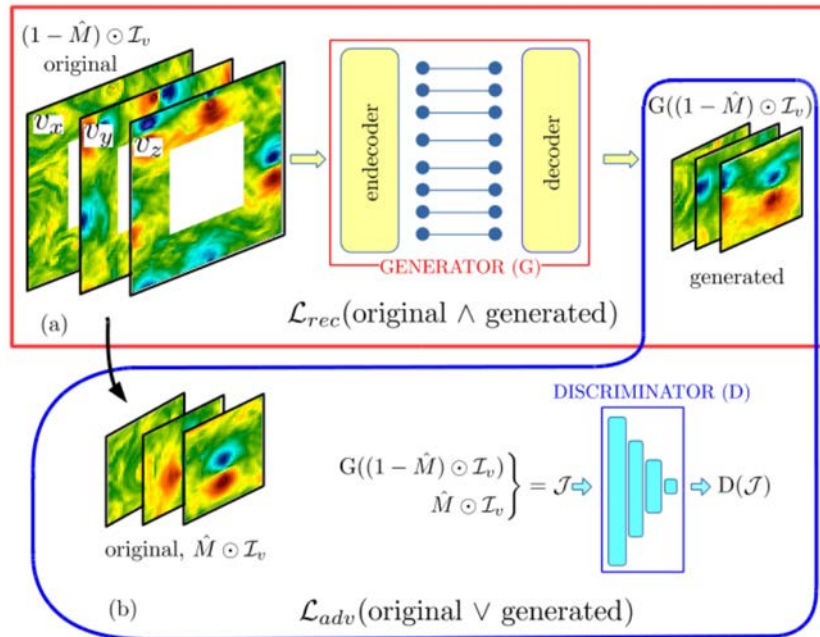


COMPARISON GAN/DM



STATISTICAL RECONSTRUCTION ENERGY SPECTRA

GAN/DM



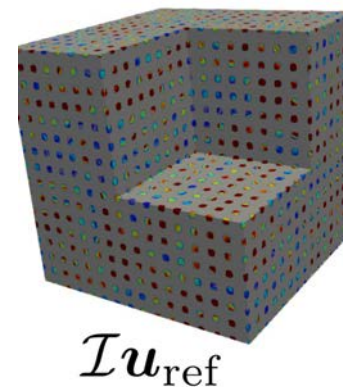
GAN/DM

- EQUATION-FREE
- DATA HUNGRY
- MISSING PHYSICS (SEE LATER)
- +ONCE TRAINED $\rightarrow$ INSTANTANEOUS
- +MIXED INPUT FEATURES
- +OK STATISTICAL UNCERTAINTIES

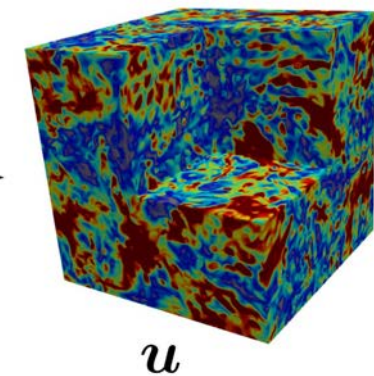
NUDGING

$$\begin{cases} \partial_t \mathbf{v} + \mathbf{v} \cdot \partial_{\mathbf{x}} \mathbf{v} + \partial_{\mathbf{x}} P - \nu \Delta \mathbf{v} = 2\mathbf{v} \times \boldsymbol{\Omega} + \mathcal{S}\mathbf{v} + \alpha g \hat{\mathbf{z}} T + \mathcal{F} - N(\mathbf{v}_N - \mathbf{v}) \\ \partial_t T + \mathbf{v} \cdot \partial_{\mathbf{x}} T - \chi \Delta T = \mathcal{G}v_z + \mathcal{L} - N_T(T_N - T) \end{cases}$$

Nudging field



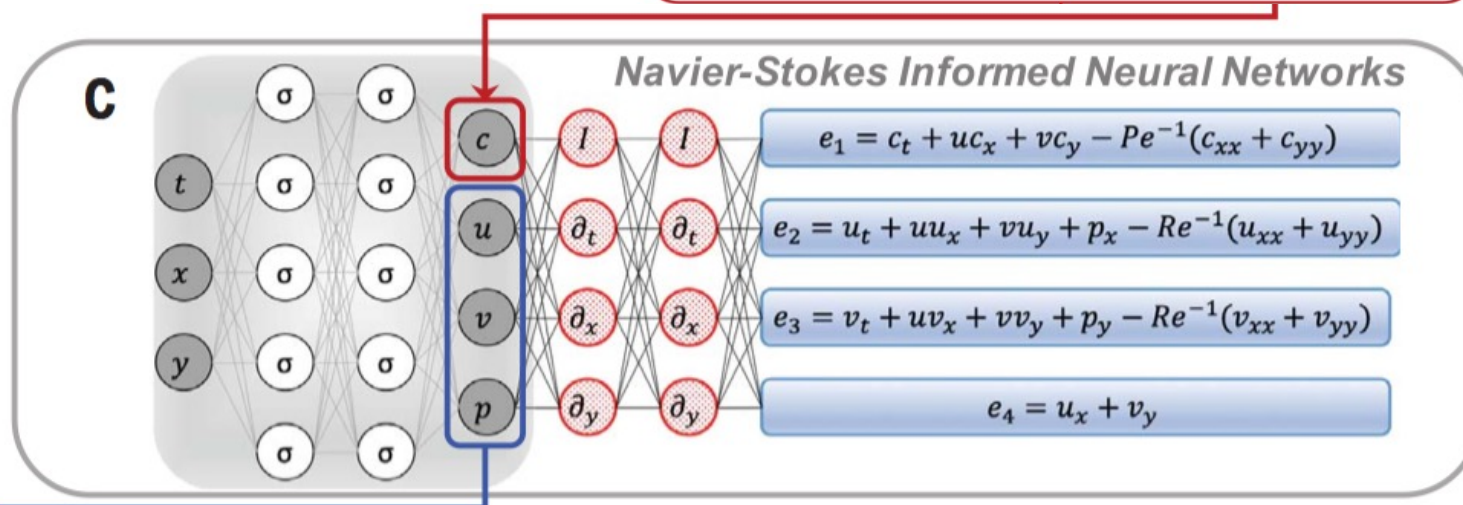
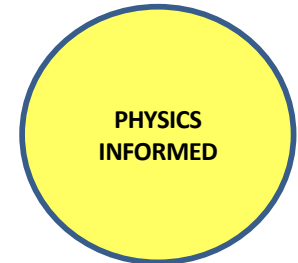
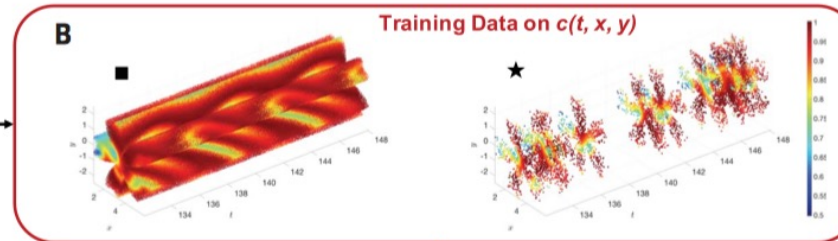
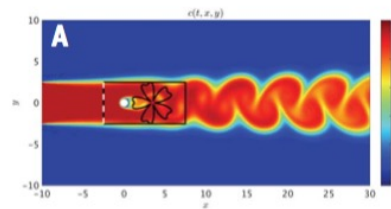
Nudged simulation



Nudge $\rightarrow$

NUDGING

- NEEDS EQUATIONS
- CPU HUNGRY
- RESTRICTED INPUT FEATURES
- +PHYSICS COMPLIANT
- +NO TRAINING
- +OK STATISTICAL UNCERTAINTIES



$$MSE = \frac{1}{N} \sum_{n=1}^N |c(t^n, x^n, y^n, z^n) - c^n|^2 + \sum_{i=1}^5 \frac{1}{M} \sum_{m=1}^M |e_i(t^m, x^m, y^m, z^m)|^2$$

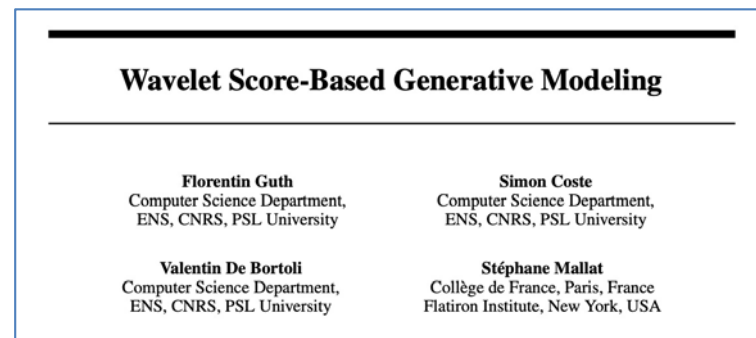
ML-TRAINED ON A SPARSE SPATIO+TEMPORAL DATASET FOR CONCENTRATION -> INFER VELOCITY + PRESSURE -> BACK PROPAGATE FOR GRADIENTS (**AUTOMATIC DIFFERENTIATION**)-> NAVIER-STOKES

WHAT WE HAVE:

- + “QUICK” STOCHASTIC TOOL TO GENERATE/AUGMENT REALISTIC 3D EULERIAN CONFIGURATIONS AND 3D LAGRANGIAN TRAJECTORIES IN TURBULENCE, EASY TO GENERALISE FOR DIFFERENT APPLICATIONS
- + HIGH QUANTITATIVE AGREEMENT WITH MULTI-SCALE STATISTICAL PROPERTIES

WHAT WE MISS:

- UNDERSTANDING OF ROBUSTNESS IN GENERALISING OUT-OF-SAMPLE: EXTREME EVENTS, DIFFERENT REYNOLDS NUMBERS & DIFFERENT FLUIDS PROPERTIES
- UNDERSTANDING SCALING PROPERTIES FOR TIME-TO-SOLUTION AT CHANGING IN-SAMPLE PROPERTIES, I.E. AT CHANGING DIMENSION OF THE TRAINING DATASET, SETS OF HYPER-PARAMETERS, CNN ARCHITECTURES: GAN, DM, TRANSFORMERS
- WHAT-IF QUESTIONS: EXPLICABILITY OF THE GENERATED DATA, FEATURES RANKINGS, PHYSICS DISCOVERY



[arxiv 2208.05003](https://arxiv.org/abs/2208.05003)



Guide for users

TURB-ROT. A LARGE DATABASE OF 3D AND 2D SNAPSHOTS FROM TURBULENT ROTATING FLOWS

A PREPRINT

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What is **Smart-TURB**? It is a brand new software infrastructure (born June 2020) for the research community working on turbulence and complex flows with particular emphasis to collect/standardize and preserve huge datasets of big-data and Machine Learning approaches to fluid mechanics in general. In particular, it is an easily accessible web platform for high quality data. It is designed to host, standardize and manage a large collection of experimental and numerical data sets from high-end fluid dynamics facilities and High Performance Computational centers. Smart-TURB offers excellent performances when accessing/uploading/searching data. The research community is asked to contribute, by deploying freely downloadable, accurate and documented dataset for the sake of "reproducibility": The process of documenting procedures and archiving data so that others can fully reproduce scientific results. Please contact the administrator for infos about how to upload your dataset. We achieved this by deploying a first dataset made of 2d and 3d turbulent configurations under the name of TURB-Rot. More will come.

<https://smart-turb.roma2.infn.it/>

Search for datasets

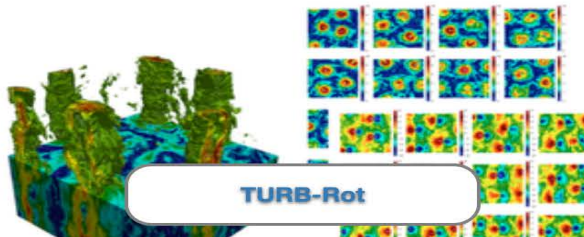


1

Datasets

TURB-Rot

A large database of 3d and 2d snapshots from turbulent rotating



2

Organizations

web_admin
web_admin group

1
member